

CHAPTER 8

PILOTING

DEFINITION AND PURPOSE

800. Introduction

Piloting involves navigating a vessel in restricted waters and fixing its position as precisely as possible at frequent intervals. More so than in other phases of navigation, proper preparation and attention to detail are important. This chapter will discuss a piloting methodology designed to ensure that procedures are carried out safely and efficiently. These procedures will vary from vessel to vessel according to the skills and composition of the piloting team. It is the responsibility of the navigator to choose the procedures applicable to his own situation, to train the piloting team in their execution, and to ensure that duties are carried out properly.

These procedures are written primarily from the perspective of the military navigator, with some notes included where civilian procedures might differ. This set of procedures is designed to minimize the chance of error and maximize safety of the ship.

The military navigation team will nearly always consist of several more people than are available to the civilian navigator. Therefore, the civilian navigator must streamline these procedures, eliminating certain steps, doing only what is essential to keep his ship in safe water.

The navigation of civilian vessels will therefore proceed differently than for military vessels. For example, while the military navigator might have bearing takers stationed at the gyro repeaters on the bridge wings for taking simultaneous

bearings, the civilian navigator must often take and plot them himself. While the military navigator will have a bearing book and someone to record entries for each fix, the civilian navigator will simply plot the bearings on the chart as they are taken and not record them at all.

If the ship is equipped with an ECDIS, it is reasonable for the navigator to simply monitor the progress of the ship along the chosen track, visually ensuring that the ship is proceeding as desired, checking the compass, sounder and other indicators only occasionally. If a pilot is aboard, as is often the case in the most restricted of waters, his judgement can generally be relied upon explicitly, further easing the workload. But should the ECDIS fail, the navigator will have to rely on his skill in the manual and time-tested procedures discussed in this chapter.

While an ECDIS is the legal equivalent of a paper chart and can be used as the primary plot, an ECS, (non-ECDIS compliant electronic chart system) cannot be so used. An ECS may be considered as an additional resource used to ensure safe navigation, but cannot be relied upon for performing all the routine tasks associated with piloting. The individual navigator, with knowledge of his vessel, his crew, and the capabilities they possess, must make a professional judgement as to how the ECS can support his efforts to keep his ship in safe water. The navigator should always remember that reliance on any single navigation system courts disaster. An ECS does not relieve the navigator of maintaining a proper and legal plot on a paper chart.

PREPARATION

801. Plot Setup

The navigator's job begins well before getting underway. Much advance preparation is necessary to ensure a safe and efficient voyage. The following steps are representative:

Ensure the plotting station(s) have the following instruments:

- **Dividers:** Dividers are used to measure distances between points on the chart.
- **Compasses:** Compasses are used to plot range arcs for radar LOP's. **Beam compasses** are used when the range arc exceeds the spread of a conventional

compass. Both should be available at both plots.

- **Plotters:** Several types of plotters are available. The preferred device for large vessels is the parallel motion plotter (PMP) used in conjunction with a drafting table. Otherwise, use a transparent protractor plotter, or triangles, parallel rulers or rolling rulers in conjunction with the chart's compass rose. Finally, the plotter can use a one arm protractor. The plotter should use the device with which he can work the most quickly and accurately.
- **Sharpened Pencils and Erasers:** Ensure an adequate supply of pencils is available.

- **Fischer Radar Plotting Templates:** Fischer plotting is covered in Chapter 13. The plotting templates for this technique should be stacked near the radar repeater.
- **Time-Speed-Distance Calculator:** Given two of the three unknowns (between time, speed, and distance), this calculator allows for rapid computation of the third.
- **Tide and Current Graphs:** Post the tide and current graphs near the primary plot for easy reference during the transit. Give a copy of the graphs to the conning officer and the captain.

Once the navigator verifies the above equipment is in place, he tapes down the charts on the chart table. If more than one chart is required for the transit, tape the charts in a stack such that the plotter works from the top to the bottom of the stack. This minimizes the time required to shift the chart during the transit. If the plotter is using a PMP, align the arm of the PMP with any meridian of longitude on the chart. While holding the PMP arm stationary, adjust the PMP to read 000.0°T. This procedure calibrates the PMP to the chart in use. Perform this alignment every time the piloting team shifts charts.

Be careful not to fold under any important information when folding the chart on the chart table. Ensure the chart's distance scale, the entire track, and all important warning information are visible.

Energize and test all electronic navigation equipment, if not already in operation. This includes the radar and the GPS receiver. Energize and test the fathometer. Ensure the entire electronic navigation suite is operating properly prior to entering restricted waters.

802. Preparing Charts and Publications

- **Assemble Required Publications.** These publications should include *Coast Pilots*, *Sailing Directions*, *USCG Light Lists*, *NIMA Lists of Lights*, *Tide Tables*, *Tidal Current Tables*, *Notice to Mariners*, and *Local Notice to Mariners*. Often, for military vessels, a port will be under the operational direction of a particular squadron; obtain that squadron's port Operation Order. Civilian vessels should obtain the port's harbor regulations. These publications will cover local regulations such as speed limits and bridge-to-bridge radio frequency monitoring requirements. Assemble and review the Broadcast Notice to Mariners file.
- **Select and Correct Charts.** Choose the largest scale chart available for the harbor approach or departure. Often, the harbor approach will be too long to be represented on only one chart. For example, three charts are required to cover the waters from the Naval Station in Norfolk to the entrance of the Chesapeake

Bay. Therefore, obtain all the charts required to cover the entire passage. Using the *Notice to Mariners*, verify that these charts have been corrected through the latest *Notice to Mariners*. Check the *Local Notice to Mariners* and the Broadcast Notice to Mariners file to ensure the chart is fully corrected. Annotate on the chart or a chart correction card all the corrections that have been made; this will make it easier to verify the chart's correction status prior to its next use. Naval ships may need to prepare three sets of charts. One set is for the primary plot, the second set is for the secondary plot, and the third set is for the conning officer and captain. Civilian vessels will prepare one set.

- **Mark the Minimum Depth Contour:** Determine the minimum depth of water in which the vessel can safely operate and outline that depth contour on the chart. Do this step before doing any other harbor navigation planning. Highlight this outline in a bright color so that it clearly stands out. Carefully examine the area inside the contour and mark the isolated shoals less than the minimum depth which fall inside the marked contour. Determine the minimum depth in which the vessel can operate as follows:

Minimum Depth = Ship's Draft – Height of Tide + Safety Margin + Squat. (See Article 804 and Article 818.)

Remember that often the fathometer's transducer is not located at the section of the hull that extends the furthest below the waterline. Therefore, the indicated depth of water is that below the fathometer transducer, not the depth of water below the vessel's deepest draft.

- **Highlight Selected Visual Navigation Aids (NAVAIDS).** Circle, highlight and label the main navigational aids on the chart. Consult the applicable *Coast Pilot* or *Sailing Directions* to determine a port's best NAVAIDS if the piloting team has not visited the port previously. These aids can be lighthouses, piers, shore features, or tanks; any prominent feature that is displayed on the chart can be used as a NAVAID. Label critical buoys, such as those marking a harbor entrance or a traffic separation scheme. Verify charted lights against the *Light List* or the *List of Lights* to confirm the charted information is correct. This becomes most critical when attempting to identify a light at night. Label NAVAIDS succinctly and clearly. Ensure everyone in the navigation team refers to a NAVAID using the same terminology. This will reduce confusion between the bearing taker, the bearing recorder, and plotter.
- **Highlight Selected Radar NAVAIDS.** Highlight radar NAVAIDS with a triangle instead of a circle. If

the NAVAID is suitable for either visual or radar piloting, it can be highlighted with either a circle or a triangle.

- Plot the Departure/Approach Track.** This process is critical for ensuring safe pilotage. Consult the *Fleet Guide* and *Sailing Directions* for recommendations on the best track to use. Look for any information or regulations published by the local harbor authority. Lacking any of this information, locate a channel or safe route on the chart and plot the vessel's track. Most U.S. ports have well-defined channels marked with buoys. Carefully check the intended track to ensure a sufficient depth of water under the keel will exist for the entire passage. If the scale of the chart permits, lay the track out to the starboard side of the channel to allow for any vessel traffic proceeding in the opposite direction. Many channels are marked by natural or man-made ranges. The bearings of these ranges should be measured to the nearest 0.1° or noted from the *Light List*, and this value should be marked on the chart. Not only are ranges useful in keeping a vessel on track, they are invaluable for determining gyro error. See Article 807.
- Label the Departure/Approach Track.** Label the track course to the nearest 0.5° . Similarly, label the distance of each track leg. Highlight the track courses for easy reference while piloting. Often a navigator might plan two separate tracks. One track would be for use during good visibility and the other for poor visibility. Considerations might include concern for the number of turns (fewer turns for poor visibility) or proximity to shoal water (smaller margin for error might be acceptable in good visibility). In this case, label both tracks as above and appropriately mark when to use each track.
- Use Advance and Transfer to Find Turning Points.** The distance the vessel moves along its original course from the time the rudder is put over until the new course is reached is called **advance**. The distance the vessel moves perpendicular to the original course during the turn is called **transfer**. The track determined above does not account for these. See Figure 802a. Use the advance and transfer characteristics of the vessel to determine when the vessel must put its rudder over to gain the next course. From that point, fair in a curve between the original course and the new course. Mark the point on the original course where the vessel must put its rudder over as the **turning point**. See Figure 802b.
- Plot Turn Bearings and Ranges.** A **turn bearing** is a predetermined bearing to a charted object from the track point at which the rudder must be put over in order to make a desired turn. In selecting a NAVAID

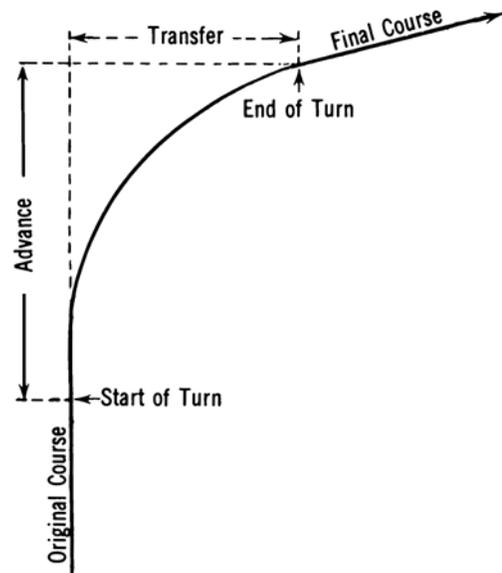


Figure 802a. Advance and transfer.

for a turn bearing, find one as close to abeam as possible at the turning point, and if possible on the inside elbow of the turn. Account for advance and transfer and label the bearing to the nearest 0.1° . A **turn range** is similar, but taken as a radar range to a prominent object ahead or astern. Ideally, both can be used, one as a check against the other.

Example: Figure 802b illustrates using advance and transfer to determine a turn bearing. A ship proceeding on course 100° is to turn 60° to the left to come on a range which will guide it up a channel. For a 60° turn and the amount of rudder used, the advance is 920 yards and the transfer is 350 yards.

Required: The bearing of flagpole "FP." when the rudder is put over.

Solution:

1. Extend the original course line, AB.
2. At a perpendicular distance of 350 yards, the transfer, draw a line A'B' parallel to the original course line AB. The point of intersection, C, of A'B' with the new course line is the place at which the turn is to be completed.
3. From C draw a perpendicular, CD, to the original course line, intersecting at D.
4. From D measure the advance, 920 yards, back along the original course line. This locates E, the point at which the turn should be started.
5. The direction of "FP." from E, 058° , is the bearing when the turn should be started.

Answer: Bearing 058° .

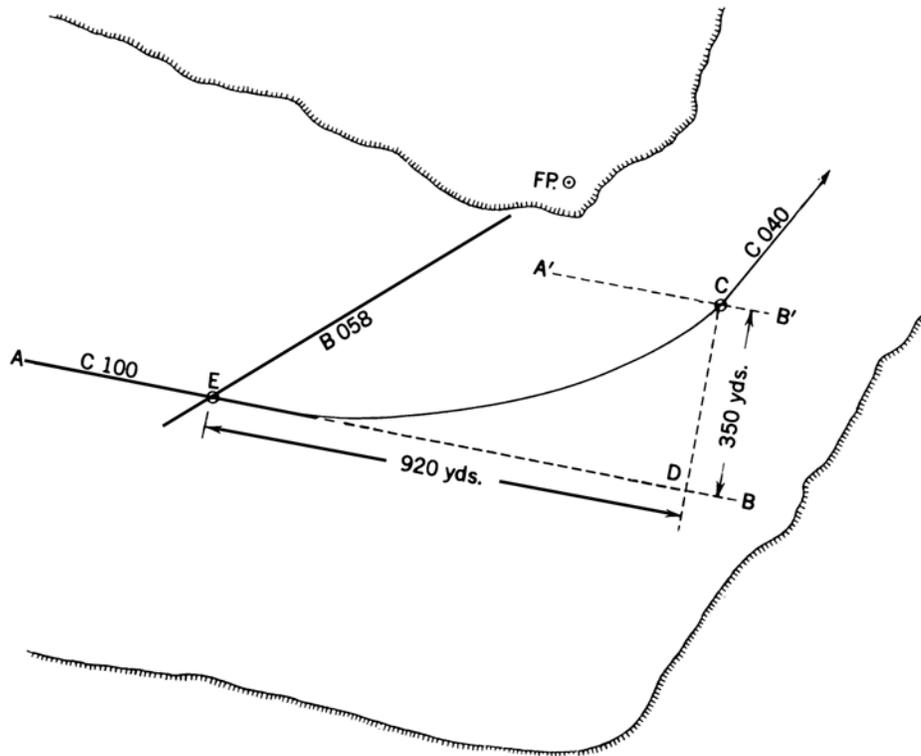


Figure 802b. Allowing for advance and transfer.

- Plot a Slide Bar for Every Turn Bearing:** If the ship is off track immediately prior to a turn, a plotting technique known as the **slide bar** can quickly revise a turn bearing. See Figure 802c. A slide bar is a line drawn parallel to the new course through the turning point on the original course. The navigator can quickly determine a new turn bearing by dead reckoning ahead from the vessel's last fix position to where the DR intersects the slide bar. The revised turn bearing is simply the bearing from that intersection point to the turn bearing NAVAID. Draw the slide bar with a different color from that used for the track in order to see the slide bar clearly.
- Label Distance to Go from Each Turn Point:** At each turning point, label the distance to go until either the ship moors (inbound) or the ship clears the harbor (outbound). For an inbound transit, a vessel's captain is usually more concerned about time of arrival, so assume a speed of advance and label each turn point with time to go until mooring.
- Plot Danger Bearings:** Danger bearings warn a navigator he may be approaching a navigational hazard too closely. See Figure 802d. Vector AB indicates a vessel's intended track. This track passes close to the indicated shoal. Draw a line from the NAVAID H tangent to the shoal. The bearing of that tangent line measured from the ship's track is 074.0°T . In other words, as long as NAVAID H bears *less than* 074°T as the vessel proceeds down its track, the vessel will not ground on the shoal. Hatch the side of the bearing line on the side of the hazard and label the danger bearing NMT (no more than) 074.0°T . For an added margin of safety, the line does not have to be drawn exactly tangent to the shoal. Perhaps, in this case, the navigator might want to set an error margin and draw the danger bearing at 065°T from NAVAID H. Lay down a danger bearing from any appropriate NAVAID in the vicinity of any hazard to navigation. Ensure the track does not cross any danger bearing.
- Plot Danger Ranges:** The danger range is analogous to the danger bearing. It is a standoff range from an object to prevent the vessel from approaching a hazard too closely.
- Label Warning and Danger Soundings:** To determine the danger sounding, examine the vessel's proposed track and note the minimum expected sounding. The minimum expected sounding is the difference between the shallowest water expected on the transit and the vessel's maximum draft. Set 90% of this difference as the warning sounding and 80% of this difference as the danger sounding. There may be peculiarities about local conditions that will cause the navigator to choose another method of setting warning and danger soundings. Use the above method if no

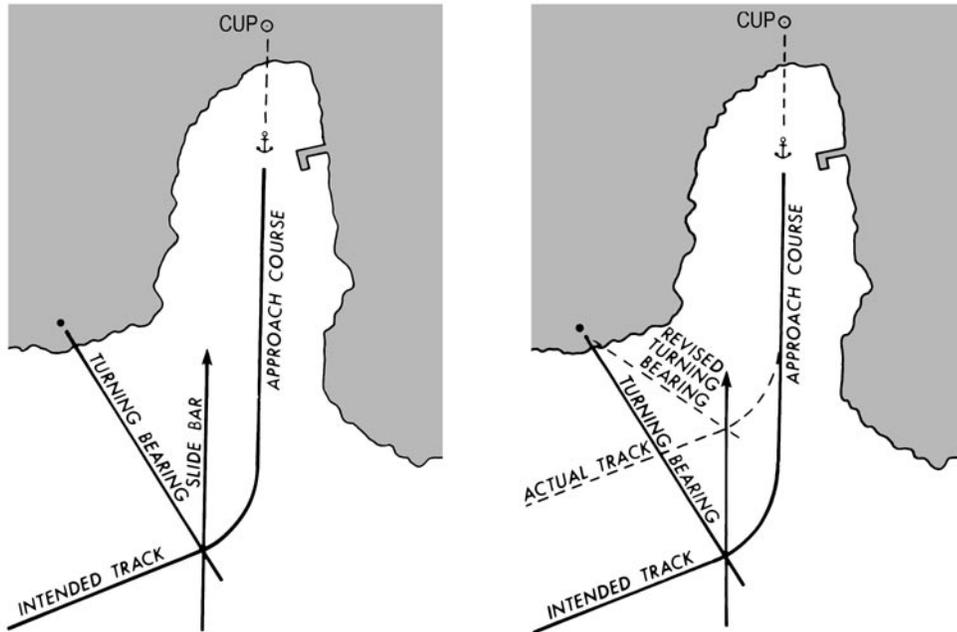


Figure 802c. The slide bar technique.

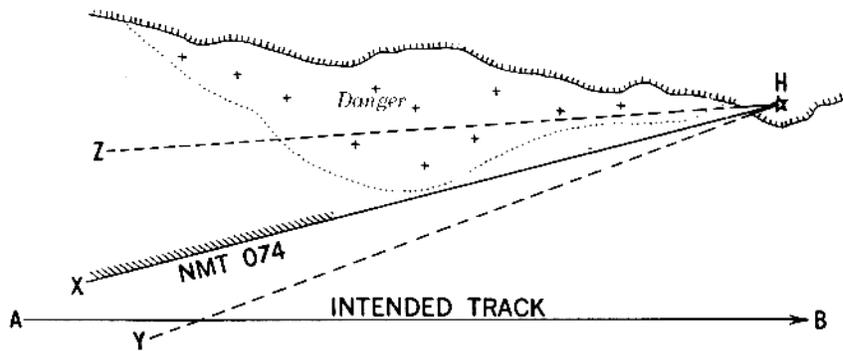


Figure 802d. A danger bearing, hatched on the dangerous side, labeled with the appropriate bearing.

other means is more suitable. For example: A vessel draws a maximum of 20 feet, and it is entering a channel dredged to a minimum depth of 50 feet. Set the warning and danger soundings at 0.9 (50ft. - 20ft) = 27ft and 0.8 (50ft. - 20ft.) = 24ft., respectively. Re-evaluate these soundings at different intervals along the track, when the minimum expected sounding may change. Carefully label the points along the track between which these warning and danger soundings apply.

- **Label Demarcation Line:** Clearly label the point on the ship's track where the Inland and International Rules of the Road apply. This is applicable only when piloting in U.S. ports.

- **Mark Speed Limits Where Applicable:** Often a harbor will have a local speed limit in the vicinity of piers, other vessels, or shore facilities. Mark these speed limits and the points between which they are applicable on the chart.
- **Mark the Point of Pilot Embarkation:** Some ports require vessels over a certain size to embark a pilot. If this is the case, mark the point on the chart where the pilot is to embark.
- **Mark the Tugboat Rendezvous Point:** If the vessel requires a tug to moor, mark the tug rendezvous point on the chart.
- **Mark the Chart Shift Point:** If more than one chart

will be required to complete the passage, mark the point where the navigator should shift to the next chart.

- **Harbor Communications:** Mark the point on the chart where the vessel must contact harbor control. Also mark the point where a vessel must contact its parent squadron to make an arrival report (military vessels only).
- **Tides and Currents:** Mark the points on the chart for which the tides and currents were calculated.

803. Records

Ensure the following records are assembled and personnel assigned to maintain them:

- **Bearing Record Book:** The bearing recorders for the primary and secondary plots should record all the bearings used on their plot during the entire transit. The books should clearly list what NAVAIDS are being used and what method of navigation was being used on their plot. In practice, the primary bearing book will contain mostly visual bearings and the secondary bearing book will contain mostly radar ranges and bearings.
- **Fathometer Log:** In restricted waters, monitor soundings continuously and record soundings every five minutes in the fathometer log. Record all fathometer settings that could affect the sounding display.
- **Deck Log:** This log is the legal record of the passage. Record all ordered course and speed changes. Record all the navigator's recommendations and whether the navigator concurs with the actions of the conning officer. Record all buoys passed, and the shift between different Rules of the Road. Record the name and embarkation of any pilot. Record who has the conn at all times. Record any casualty or important event. The deck log combined with the bearing log should constitute a complete record of the passage.

804. Tides and Currents

Determining the tidal and current conditions of the port is crucial. This process is covered in depth in Chapter 9. In order to anticipate early or late transit, plot a graph of the tidal range for the 24-hour period centered on the scheduled time of arrival or departure. Depending on a vessel's draft and the harbor's depth, some vessels may be able to transit only at high tide. If this is this case, it is critically important to determine the time and range of the tide correctly.

The magnitude and direction of the current will give the navigator some idea of the **set and drift** the vessel will experience during the transit. This will allow him to plan in

advance for any potential current effects in the vicinity of navigational hazards.

While printed tide tables can be used for predicting and plotting tides, it is far more efficient to use a computer with appropriate software, or the internet, to compute tides and print out the graphs. These graphs can be posted on the bridge at the chart table for ready reference, and copies made for others involved in the piloting process. NOAA tide tables for the U.S. are available at the following site: <http://co-ops.nos.noaa.gov/tp4days.html>. Always remember that tide tables give predicted data, but that actual conditions may be quite different due to weather or other natural phenomena.

805. Weather

The navigator should obtain a weather report covering the route which he intends to transit. This will allow him to prepare for any adverse weather by stationing extra lookouts, adjusting speed for poor visibility, and preparing for radar navigation. If the weather is thick, consider standing off the harbor until it clears.

The navigator can receive weather information any number of ways. Military vessels may receive weather reports from their parent squadrons prior to coming into port. Marine band radio carries continuous weather reports. Many vessels are equipped with weather facsimile machines. Some navigators carry cellular phones to reach shoreside personnel and harbor control; these can also be used to get weather reports from NOAA weather stations. If the ship is using a weather routing service for the voyage, it should provide forecasts when asked. Finally, if the vessel has an internet connection, this is an ideal source of weather data. NOAA weather data can be obtained at: <http://www.nws.noaa.gov>. However he obtains the information, the navigator should have a good idea of the weather before entering piloting waters.

806. The Piloting Brief

Assemble the entire navigation team for a piloting brief prior to entering or leaving port. The vessel's captain and navigator should conduct the briefing. All navigation and bridge personnel should attend. The pilot, if he is already on board, should also attend. If the pilot is not onboard when the ship's company is briefed, the navigator should immediately brief him when he embarks. The pilot must know the ship's maneuvering characteristics before entering restricted waters. The briefing should cover, as a minimum, the following:

- **Detailed Coverage of the Track Plan:** Go over the planned route in detail. Use the prepared and approved chart as part of this brief. Concentrate especially on all the NAVAIDS and soundings which are being used to indicate danger. Cover the buoyage system in use and

the port's major NAVAIDS. Point out the radar NAVAIDS for the radar operator. Often, a *Fleet Guide* or *Sailing Directions* will have pictures of a port's NAVAIDS. This is especially important for the piloting party that has never transited a particular port before. If no pictures are available, consider stationing a photographer to take some for submission to NIMA.

- **Harbor Communications:** Discuss the bridge-to-bridge radio frequencies used to raise harbor control. Discuss what channel the vessel is supposed to monitor on its passage into port and the port's communication protocol.
- **Duties and Responsibilities:** Each member of the piloting team must have a thorough understanding of his duties and responsibilities. He must also understand how his part fits into the whole. The radar plotter, for example, must know if radar will be the primary or secondary source of fix information. The bearing recorder must know what fix interval the navigator is planning to use. Each person must be thoroughly briefed on his job; there is little time for questions once the vessel enters the channel.

807. Evolutions Prior to Piloting

The navigator should always accomplish the following evolutions prior to piloting:

- **Testing the Shaft on the Main Engines in the Astern Direction:** This ensures that the ship can answer a backing bell. If the ship is entering port, no special precautions are required prior to this test. If the ship is tied up at the pier preparing to get underway, exercise extreme caution to ensure no way is placed on the ship while testing the main engines.
- **Making the Anchor Ready for Letting Go:** Make the anchor ready for letting go and station a watchstander in direct communications with the bridge at the anchor windlass. Be prepared to drop anchor immediately when piloting if required to keep from drifting too close to a navigational hazard.
- **Calculate Gyro Error:** An error of greater than 1.0° T indicates a gyro problem which should be investigated prior to piloting. There are several ways to determine gyro error:
 1. Compare the gyro reading with a known accurate heading reference such as an inertial navigator. The difference in the readings is the gyro error.
 2. Mark the bearing of a charted range as the range

NAVAID's come into line and compare the gyro bearing with the charted bearing. The difference is the gyro error.

3. Prior to getting underway, plot a dockside fix using at least three lines of position. The three LOP's should intersect at a point. Their intersecting in a "cocked hat" indicates a gyro error. Incrementally adjust each visual bearing by the same amount and direction until the fix plots as a pinpoint. The total correction required to eliminate the cocked hat is the gyro error.
4. Measure a celestial body's azimuth or amplitude, or Polaris' azimuth with the gyro, and then compare the measured value with a value computed from the *Sight Reduction Tables* or the *Nautical Almanac*. These methods are covered in detail in Chapter 17.

Report the magnitude and direction of the gyro error to the navigator and captain. The direction of the error is determined by the relative magnitude of the gyro reading and the value against which it is compared. When the compass is least, the error is east. Conversely, when the compass is best, the error is west. See Chapter 6.

808. Inbound Voyage Planning

The vessel's planned estimated time of arrival (ETA) at its mooring determines the vessel's course and speed to the harbor entrance. Arriving at the mooring site on time may be important in a busy port which operates its port services on a tight schedule. Therefore, it is important to plan the arrival accurately. Take the desired time of arrival at the mooring and subtract from that the time it will take to navigate to it from the entrance. The resulting time is when you must arrive at the harbor entrance. Next, measure the distance between the vessel's present location and the harbor entrance. Determine the speed of advance (SOA) the vessel will use to make the transit to the harbor. Use the distance to the harbor and the SOA to calculate what time to leave the present position to make the mooring ETA, or what speed must be made good to arrive on time.

Consider these factors which might affect this decision:

- **Weather:** This is the single most important factor in harbor approach planning because it directly affects the vessel's SOA. The thicker the weather, the more slowly the vessel must proceed. Therefore, if heavy fog or rain is in the forecast, the navigator must allow more time for the transit.
- **Mooring Procedures:** The navigator must take more than distance into account when calculating how long it will take him to pilot to his mooring. If the vessel needs a

tug, that will increase the time needed. Similarly, picking up or dropping off a pilot adds time to the transit. It is better to allow a margin for error when trying to add up all the time delays caused by these procedures. It is always easier to avoid arriving early by slowing down than it is to

make up lost time by speeding up.

- **Shipping Density:** Generally, the higher the shipping density entering and exiting the harbor, the longer it will take to proceed into the harbor entrance safely.

TRANSITION TO PILOTING

809. Stationing the Piloting Team

At the appropriate time, station the piloting team. Allow plenty of time to acclimate to the navigational situation and if at night, to the darkness. The number and type of personnel available for the piloting team depend on the vessel. A Navy warship, for example, has more people available for piloting than a merchant ship. Therefore, more than one of the jobs listed below may have to be filled by a single person. The piloting team should consist of:

- **The Captain:** The captain is ultimately responsible for the safe navigation of his vessel. His judgment regarding navigation is final. The piloting team acts to support the captain, advising him so he can make informed decisions on handling his vessel.
- **The Pilot:** The pilot is usually the only member of the piloting team not a member of the ship's company. The piloting team must understand the relationship between the pilot and the captain. The pilot is perhaps the captain's most important navigational advisor. Generally, the captain will follow his recommendations when navigating an unfamiliar harbor. The pilot, too, bears some responsibility for the safe passage of the vessel; he can be censured for errors of judgment which cause accidents. However, the presence of a pilot in no way relieves the captain of his ultimate responsibility for safe navigation. The piloting team works to support and advise the captain.
- **The Officer of the Deck (Conning Officer):** In Navy piloting teams, neither the pilot or the captain usually has the **conn**. The officer having the conn directs the ship's movements by rudder and engine orders. Another officer of the ship's company usually fulfills this function. The captain can take the conn immediately simply by issuing an order to the helm should an emergency arise. The conning officer of a merchant vessel can be either the pilot, the captain, or another watch officer. In any event, the officer having the conn must be clearly indicated in the ship's deck log at all times. Often a single officer will have the deck and the conn. However, sometimes a junior officer will take the conn for training. In this case, different officers will have the deck and the conn. The officer who retains the deck retains the responsibility for the vessel's safe navigation.
- **The Navigator:** The vessel's navigator is the officer directly responsible to the ship's captain for the safe navigation of the ship. He is the captain's principal navigational advisor. The piloting team works for him. He channels the required information developed by the piloting team to the ship's conning officer on recommended courses, speeds, and turns. He also carefully looks ahead for potential navigational hazards and makes appropriate recommendations. He is the most senior officer who devotes his effort exclusively to monitoring the navigation picture. The captain and the conning officer are concerned with all aspects of the passage, including contact avoidance and other necessary ship evolutions (making up tugs, maneuvering alongside a small boat for personnel transfers, engineering evolutions, and coordinating with harbor control via radio, for example). The navigator, on the other hand, focuses solely on safe navigation. It is his job to anticipate dangers, keep himself apprised of the navigation situation at all times, and manage the team.
- **Bearing Plotting Team:** This team consists, ideally, of three persons. The first person measures the bearings. The second person records the bearings in an official record book. The third person plots the bearings. The more quickly and accurately this process is completed, the sooner the navigator has an accurate picture of the ship's position. The bearing taker should be an experienced individual who has traversed the port before and who is familiar with the NAVAIDS. He should take his round of bearings as quickly as possible, beam bearings first, minimizing any time delay errors in the resulting fix. The plotter should also be an experienced individual who can quickly and accurately lay down the required bearings. The bearing recorder can be one of the junior members of the piloting team.
- **The Radar Operator:** The radar operator has one of the more difficult jobs of the team. The radar is as important for collision avoidance as it is for navigation. Therefore, this operator must often "time share" the radar between these two functions. Determining the amount of time spent on these functions falls within the judgment of the captain and the navigator. If the day is clear and the traffic heavy, the captain may want to use the radar mostly for

collision avoidance. As the weather worsens, obscuring visual NAVAIDS, the importance of radar for safe navigation increases. The radar operator must be given clear guidance on how the captain and navigator want the radar to be operated.

- **Plot Supervisors:** On many military ships, the piloting team will consist of two plots: the primary plot and the secondary plot. The navigator should designate the type of navigation that will be employed on the primary plot. All other fix sources should be plotted on the secondary plot. The navigator can function as the primary plot supervisor. A senior, experienced individual should be employed as a secondary plot supervisor. The navigator should frequently compare the positions plotted on both plots as a check on the primary plot.

There are three major reasons for maintaining a primary and secondary plot. First, as mentioned above, the secondary fix sources provide a good check on the accuracy of visual piloting. Large discrepancies between visual and radar positions may point out a problem with the visual fixes that the navigator might not otherwise suspect. Secondly, the navigator often must change the primary means of navigation during the transit. He may initially designate visual bearings as the primary fix method only to have a sudden storm or fog obscure the visual NAVAIDS. If he shifts the primary fix means to radar, he has a track history of the correlation between radar and visual fixes. Finally, the piloting team often must shift charts several times during the transit. When the old chart is taken off the plotting table and before the new chart is secured, there is a period of time when no chart is in use. Maintaining a secondary plot eliminates this complication. Ensure the secondary plot is not shifted prior to getting the new primary plot chart down on the chart table. In this case, there will always be a chart available on which to pilot. Do not consider the primary chart shifted until the new chart is properly secured and the plotter has transferred the last fix from the original chart onto the new chart.

- **Satellite Navigation Operator:** This operator normally works for the secondary plot supervisor. GPS accuracy with Selective Availability (SA) on is not sufficient for navigating restricted waters; but with SA off, GPS can support harbor navigation, in which case it should be considered as only one aid to navigation, not as a substitute for the entire process. If the team loses visual bearings in the channel and no radar NAVAIDS are available, GPS may be the most accurate fix source available. The navigator must have some data on the comparison between satellite positions and visual positions over the history of the passage to use satellite positions effectively. The only

way to obtain this data is to plot satellite positions and compare these positions to visual positions throughout the harbor passage.

- **Fathometer Operator:** Run the fathometer continuously and station an operator to monitor it. Do not rely on audible alarms to key your attention to this critically important piloting tool. The fathometer operator must know the warning and danger soundings for the area the vessel is transiting. Most fathometers can display either total depth of water or depth under the keel. Set the fathometer to display depth under the keel. The navigator must check the sounding at each fix and compare that value to the charted sounding. A discrepancy between these values is cause for immediate action to take another fix and check the ship's position.

810. Harbor Approach (Inbound Vessels Only)

The piloting team must make the transition from coastal navigation to piloting smoothly as the vessel approaches restricted waters. There is no rigid demarcation between coastal navigation and piloting. Often visual NAVAIDS are visible miles from shore where Loran and GPS are easier to use. The navigator should take advantage of this overlap when approaching the harbor. Plotting Loran, GPS, and visual fixes concurrently ensures that the piloting team has correctly identified NAVAIDS and that the different types of systems are in agreement. Once the vessel is close enough to the shore such that sufficient NAVAIDS (at least three with sufficient bearing spread) become visible, the navigator should order visual bearings only for the primary plot and shift all other fixes to the secondary plot, unless the decision has been made to proceed with ECDIS as the primary system.

Take advantage of the coastal navigation and piloting overlap to shorten the fix interval gradually. The navigator must use his judgment in adjusting fix intervals. If the ship is steaming inbound directly towards the shore, set a fix interval such that two fix intervals lie between the vessel and the nearest danger. Upon entering restricted waters, the piloting team should be plotting visual fixes at three minute intervals.

Commercial vessels with GPS and/or Loran C, planning the harbor transit with a pilot, will approach a coast differently. The transition from ocean to coastal to harbor approach navigation will proceed as visual aids and radar targets appear and are plotted. With GPS or ECDIS operating and a waypoint set at the pilot station, only a few fixes are necessary to verify that the GPS position is correct. Once the pilot is aboard, the captain/pilot team may elect to navigate visually, depending on the situation.

TAKING FIXES WHILE PILOTING

Safe navigation while piloting requires frequent fixing of the ship's position. If ECDIS is the primary navigation system in use, this process is automatic, and the role of the navigator is to monitor the progress of the vessel, cross-check the position occasionally, and be alert for any indication that the system is not operating optimally.

If an ECS is in use, it should be considered only a supplement to the paper navigation plot, which legally must still be maintained. As long as the manual plot and the ECS plot are in agreement, the ECS is a valuable tool which shows the navigator where the ship is at any instant, not two or three minutes ago when the last fix was taken. It cannot legally take the place of the paper chart and the manual plot, but it can provide an additional measure of assurance that the ship is in safe water and alert the navigator to a developing dangerous situation before the next round of bearings or ranges.

The next several articles will discuss the three major manual methods used to fix a ship's position when piloting: crossing lines of position, copying satellite or Loran data, or advancing a single line of position. Using one method does not exclude using other methods. The navigator must obtain as much information as possible and employ as many of these methods as necessary.

811. Types of Fixes

While the intersection of two LOP's constitutes a **fix** under one definition, and only an estimated position by another, the prudent navigator will always use at least three LOP's if they are available, so that an error is apparent if they don't meet in a point. Some of the most commonly used methods of obtaining LOP's are discussed below:

- **Fix by Bearings:** The navigator can take and plot bearings from two or more charted objects. This is the most common and often the most accurate way to fix a vessel's position. Bearings may be taken directly to charted objects, or tangents of points of land. See Figure 811a. The intersection of these lines constitutes a fix. A position taken by bearings to buoys should not be considered a fix, but an estimated position (EP), because buoys swing about their watch circle and may be out of position.

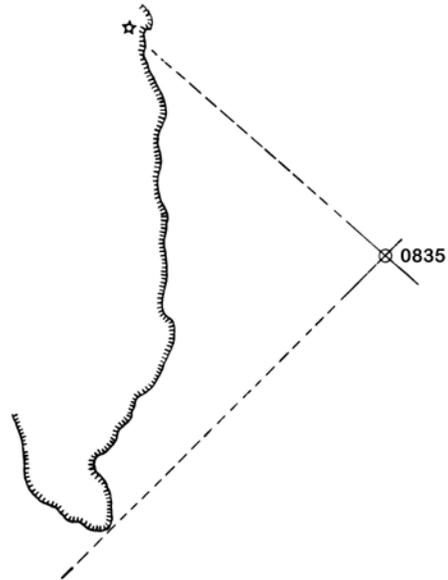


Figure 811a. A fix by two bearing lines.

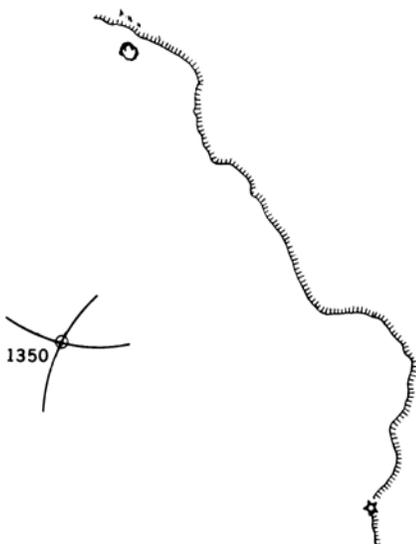


Figure 811b. A fix by two radar ranges.

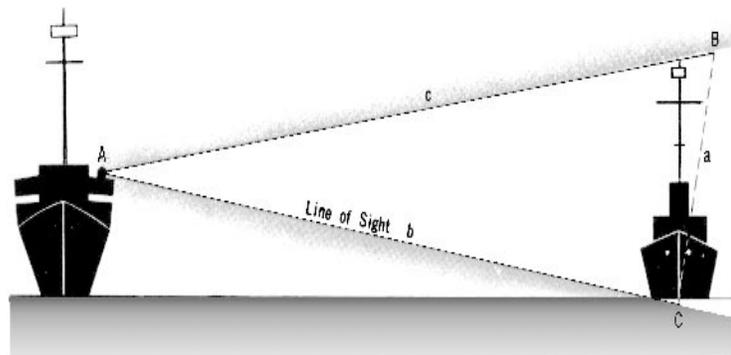


Figure 811c. Principle of stadimeter operation.

- **Fix by Ranges:** The navigator can plot a fix consisting of the intersection of two or more range arcs from charted objects. He can obtain an object's range in several ways:

1. **Radar Ranges:** See Figure 811b. The navigator may take ranges to two fixed objects. The intersection of the range arcs constitutes a fix. He can plot ranges from any point on the radar scope which he can correlate on his chart. Remember that the shoreline of low-lying land may move many yards in an area of large tidal range, and swampy areas may be indistinct.

2. **Stadimeter Ranges:** Given a known height of a NAVAID, one can use a stadimeter to determine its range. See Figure 811c for a representation of the geometry involved. Generally, stadimeters contain a height scale on which is set the height of the object. The observer then directs his line of sight through the stadimeter to the base of the object being observed. Finally, he adjusts the stadimeter's range index until the object's top reflection is "brought down" to the visible horizon. Read the object's range off the range index.

3. **Sextant Vertical Angles:** Measure the vertical angle from the top of the NAVAID to the waterline below the NAVAID. Enter Table 16 to determine the distance of the NAVAID. The navigator must know the height of the NAVAID above sea level to use this table; it can be found in the *Light List*.

4. **Sonar Ranges:** If the vessel is equipped with a sonar suite, the navigator can use sonar echoes to determine ranges to charted underwater objects. It may take some trial and error to set the active signal strength at a value that will give a strong return and still not cause excessive reverberation. Check local harbor restrictions on energizing active sonar. Avoid active sonar transmissions in the vicinity of divers.

- **Fix by Bearing and Range:** This is a hybrid fix of LOP's from a bearing and range to a single object. The radar is the only instrument that can give simultaneous range and bearing information to the same object. (A sonar system can also provide bearing and range information, but sonar bearings are far too inaccurate to use in piloting.) Therefore, with the radar, the navigator can obtain an instantaneous fix from only one NAVAID. This unique fix is shown in Figure 811d. This makes the radar an extremely useful tool for the piloting team. The radar's characteristics make it much more accurate determining range than determining

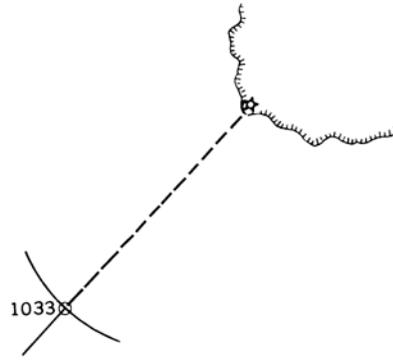


Figure 811d. A fix by range and bearing of a single object.

bearing; therefore, two radar ranges are preferable to a radar range and bearing.

- **Fix by Range Line and Distance:** When the vessel comes in line with a range, plot the bearing to the range (while checking compass error in the bargain) and cross this LOP with a distance from another NAVAID. Figure 811e shows this fix.

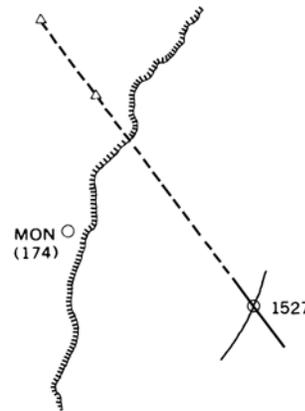


Figure 811e. A fix by a range and distance.

812. The Running Fix

When only one NAVAID is available from which to obtain bearings, use a technique known as the **running fix**. Use the following method:

1. Plot a bearing to a NAVAID (LOP 1).
2. Plot a second bearing to a NAVAID (either the same NAVAID or a different one) at a later time (LOP 2).
3. Advance LOP 1 to the time when LOP 2 was taken.
4. The intersection of LOP 2 and the advanced LOP 1 constitute the running fix.

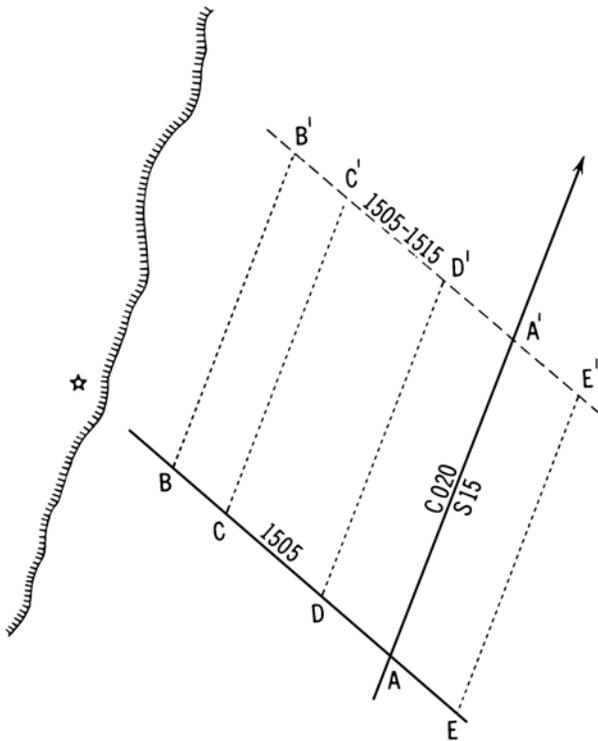


Figure 812a. Advancing a line of position.

Figure 812a represents a ship proceeding on course 020°, speed 15 knots. At 1505, the plotter plots an LOP to a lighthouse bearing 310°. The ship can be at any point on this 1505 LOP. Some possible points are represented as points A, B, C, D, and E in Figure 812a. Ten minutes later the ship will have traveled 2.5 miles in direction 020°. If the ship was at A at 1505, it will be at A' at 1515. However, if the position at 1505 was B, the position at 1515 will be B'. A similar relationship exists between C and C', D and D', E and E'. Thus, if any point on the original LOP is moved a distance equal to the distance run in the direction of the motion, a line through this point parallel to the original line of position represents all possible positions of the ship at the later time. This process is called **advancing** a line of position. Moving a line back to an earlier time is called **retiring** a line of position.

When advancing a line of position, account for course changes, speed changes, and set and drift between the two bearing lines. Three methods of advancing an LOP are discussed below:

Method 1: See Figure 812b. To advance the 1924 LOP to 1942, first apply the best estimate of set and drift to the 1942 DR position and label the resulting position point B. Then, measure the distance between the dead reckoning position at 1924 (point A) and point B. Advance the LOP a distance equal to the distance between points A and B. Note that LOP A'B' is in the same direction as line AB.

Method 2: See Figure 812c. Advance the NAVAIDS position on the chart for the course and distance traveled by the vessel and draw the line of position from the NAVAIDS

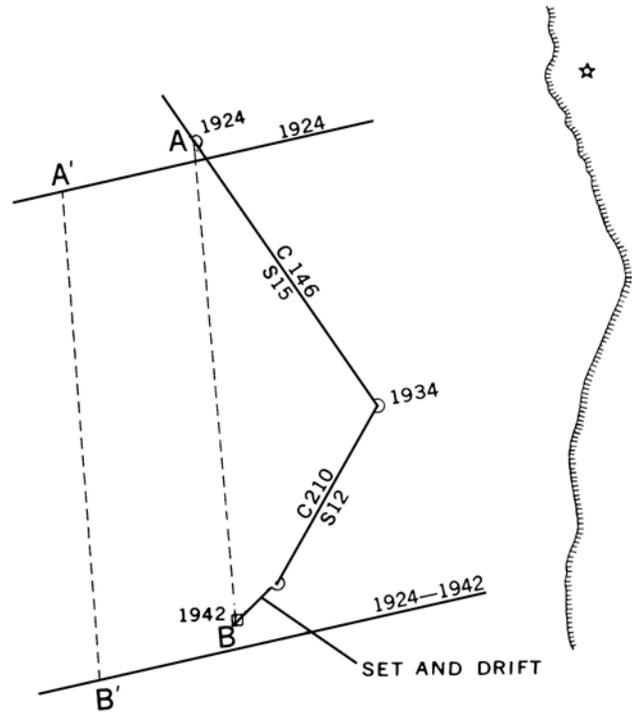


Figure 812b. Advancing a line of position with a change in course and speed, allowing for set and drift.

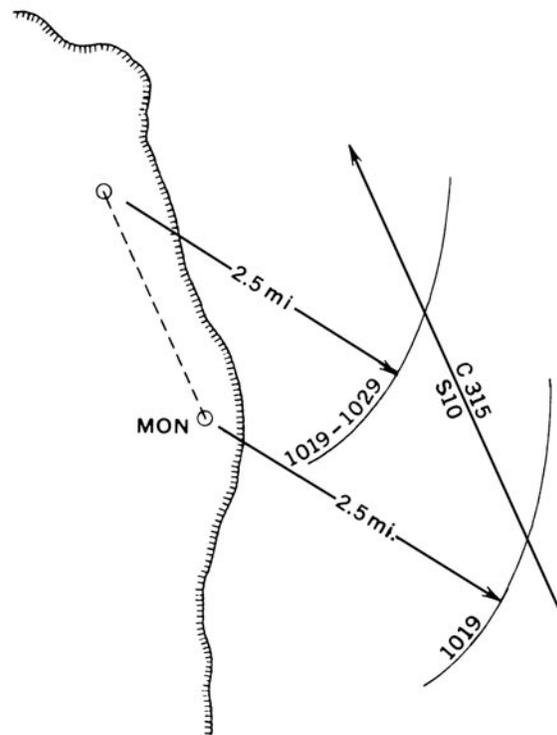


Figure 812c. Advancing a circle of position.

advanced position. This is the most satisfactory method for advancing a circle of position.

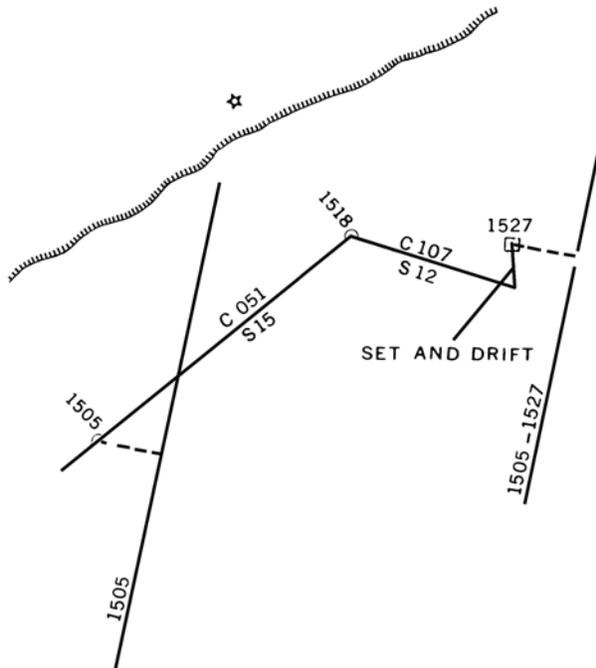


Figure 812d. Advancing a line of position by its relation to the dead reckoning.

Method 3: See Figure 812d. To advance the 1505 LOP to 1527, first draw a correction line from the 1505 DR position to the 1505 LOP. Next, apply a set and drift correction to the 1527 DR position. This results in a 1527 estimated position (EP). Then, draw from the 1527 EP a correction line of the same length and direction as the one drawn from the 1505 DR to the 1505 LOP. Finally, parallel

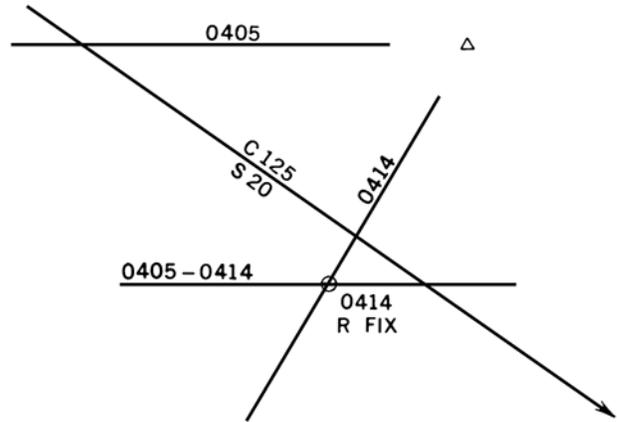


Figure 812e. A running fix by two bearings on the same object.

the 1505 bearing to the end of the correction line as shown.

Label an advanced line of position with both the time of observation and the time to which the line is adjusted.

Figure 812e through Figure 812g demonstrate three running fixes. Figure 812e illustrates the case of obtaining a running fix with no change in course or speed between taking two bearings on the same NAVAID. Figure 812f illustrates a running fix with changes in a vessel's course and speed between taking two bearings on two different objects. Finally, Figure 812g illustrates a running fix obtained by advancing range circles of position using the second method discussed above.

PILOTING PROCEDURES

The previous section discussed the methods for fixing the ship's position. This section discusses integrating the manual fix methods discussed above, and the use of the fathometer, into a piloting procedure. The navigator must develop his piloting procedure to meet several requirements. He must obtain enough information to fix the position of the vessel without question. He must also plot and evaluate this information. Finally, he must relay his evaluations and recommendations to the vessel's conning officer. This section examines some considerations to ensure the navigator accomplishes all these requirements quickly and effectively. Of course, if ECDIS is the primary plot, manual methods as discussed here are for backup use.

813. Fix Type and Fix Interval

The preferred piloting fix is taken from visual bearings from charted fixed NAVAIDS. Plot visual bearings on the primary plot and plot all other fixes on the secondary plot. If poor visibility obscures visual NAVAIDS, shift to radar

plotting on the primary plot. If neither visual or radar piloting is available, consider standing off until the visibility improves.

The interval between fixes in restricted waters should usually not exceed three minutes. Setting the fix interval at three minutes optimizes the navigator's ability to assimilate and evaluate all available information. He must relate it to charted navigational hazards and to his vessel's intended track. It should take a well trained plotting team no more than 30 seconds to measure, record, and plot three bearings to three separate NAVAIDS. The navigator should spend the majority of the fix interval time interpreting the information, evaluating the navigational situation, and making recommendations to the conning officer.

If three minutes goes by without a fix, inform the captain and try to plot a fix as soon as possible. If the delay was caused by a loss of visibility, shift to radar piloting. If the delay was caused by plotting error, take another fix. If the navigator cannot get a fix down on the plot for several more minutes, consider slowing or stopping the ship until its position can be fixed. Never continue a passage through

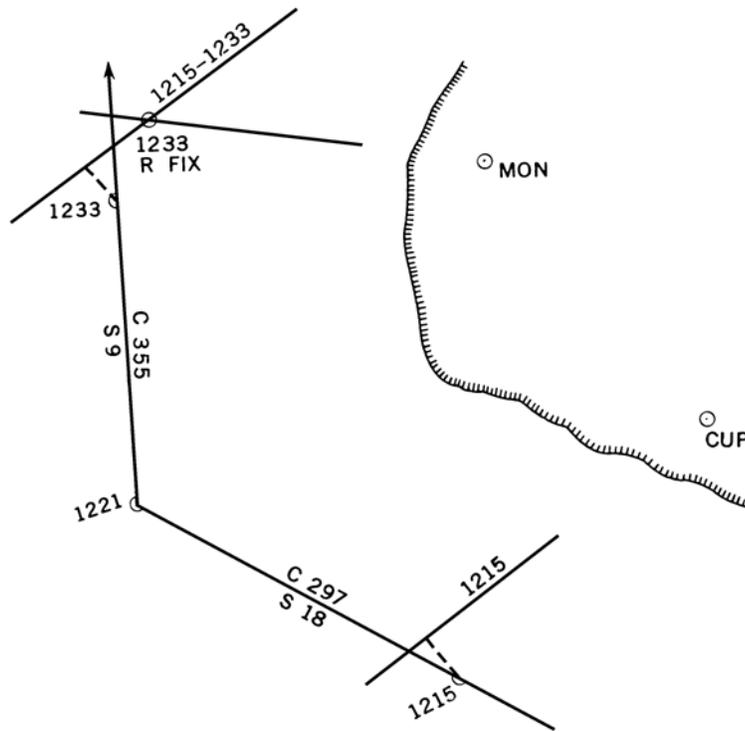


Figure 812f. A running fix with a change of course and speed between observations on separate landmarks.

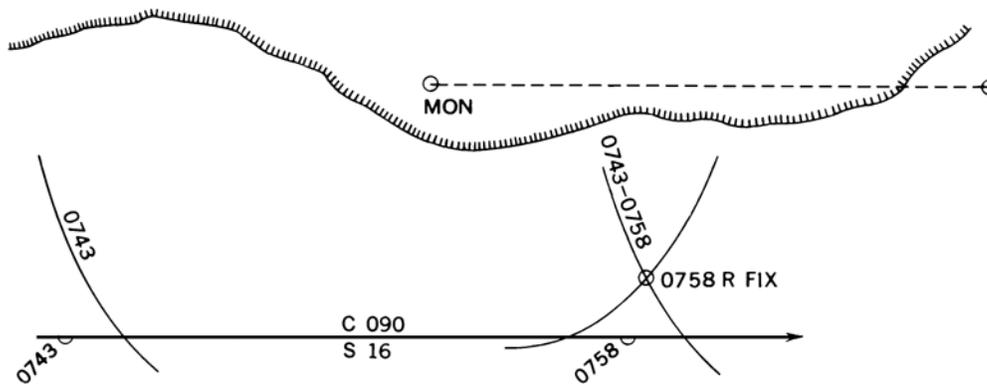


Figure 812g. A running fix by two circles of position.

restricted waters if the vessel's position is uncertain.

The secondary plot supervisor should maintain the same fix interval as the primary plot. Usually, this means he should plot a radar fix every three minutes. He should plot other fix sources (Loran and GPS fixes, for example) at an interval sufficient for making meaningful comparisons between fix sources. Every third fix interval, he should pass a radar fix to the primary plot for comparison with the visual fix. He should inform the navigator how well all the fix sources plotted on the secondary plot are tracking.

814. The Piloting Routine

Following a cyclic routine ensures the timely and efficient processing of data and forms a smoothly

functioning piloting team. It quickly yields the information which the navigator needs to make informed recommendations to the conning officer and captain.

Repeat this routine at each fix interval beginning when the ship gets underway until it clears the harbor (outbound) or when the ship enters the harbor until it is moored (inbound).

The routine consists of the following steps:

1. Take, plot and label a fix.
2. Calculate set and drift from the DR position.
3. Reset the DR from the fix and DR two fixes ahead.

• **Plotting the Fix:** This involves coordination between the navigator, bearing taker(s), recorder, and plotter.

The navigator will call for each fix at the DR time. The bearing taker must measure his bearings as quickly as possible, beam bearings first, fore and aft last, on the navigator's mark. The recorder will write the bearings in the book, and the plotter will plot them immediately.

- **Labeling the Fix:** The plotter should clearly mark a visual fix with a circle or an electronic fix with a triangle. Clearly label the time of each fix. A visual running fix should be circled, marked "R Fix" and labeled with the time of the second LOP. Keep the chart neat and uncluttered when labeling fixes.
- **Dead Reckoning Two Fix Intervals Ahead:** After labeling the fix, the plotter should dead reckon the fix position ahead two fix intervals. The navigator should carefully check the area marked by this DR for any navigational hazards. If the ship is approaching a turn, update the turn bearing as discussed in Article 802.
- **Calculate Set and Drift at Every Fix:** Calculating set and drift is covered in Chapter 7. Calculate these values at every fix and inform the captain and conning officer. Compare the actual values of set and drift with the predicted values from the current graph discussed in Article 804. Evaluate how the current is affecting the vessel's position in relation to the track and recommend courses and speeds to regain the planned track. Because the navigator can determine set and drift only when comparing fixes and DR's plotted for the same time, take fixes exactly at the times for which a DR has been plotted. Repeat this routine at each fix interval beginning when the ship gets underway until it clears the harbor (outbound) or when the ship enters the harbor until she is moored (inbound).
- **Piloting Routine When Turning:** Modify the cyclic routine slightly when approaching a turn. Adjust the fix interval so that the plotting team has a fix plotted approximately one minute before a scheduled turn. This gives the navigator sufficient time to evaluate the position in relation to the planned track, DR ahead to the slide bar to determine a new turn bearing, relay the new turn bearing to the conning officer, and then monitor the turn bearing to mark the turn.

Approximately 30 seconds before the time to turn, train the alidade on the turn bearing NAVAID. Watch the

bearing of the NAVAID approach the turn bearing. About 1° away from the turn bearing, announce to the conning officer: "Stand by to turn." Slightly before the turn bearing is indicated, report to the conning officer: "Mark the turn." Make this report slightly before the bearing is reached because it takes the conning officer a finite amount of time to acknowledge the report and order the helmsman to put over the rudder. Additionally, it takes a finite amount of time for the helmsman to turn the rudder and for the ship to start to turn. If the navigator waits until the turn bearing is indicated to report the turn, the ship will turn too late.

Once the ship is steady on the new course, immediately take another fix to evaluate the vessel's position in relation to the track. If the ship is not on the track after the turn, calculate and recommend a course to the conning officer to regain the track.

815. Using the Fathometer

Use the fathometer to determine whether the depth of water under the keel is sufficient to prevent the ship from grounding and to check the actual water depth with the charted water depth at the fix position. The navigator must compare the charted sounding at every fix position with the fathometer reading and report to the captain any discrepancies. Taking continuous soundings in restricted waters is mandatory.

See the discussion of calculating the warning and danger soundings in Article 802. If the warning sounding is received, then slow the ship, fix the ship's position more frequently, and proceed with extreme caution. Ascertain immediately where the ship is in the channel; if the minimum expected sounding was noted correctly, the warning sounding indicates the vessel may be leaving the channel and standing into shoal water. Notify the vessel's captain and conning officer immediately.

If the danger sounding is received, take immediate action to get the vessel back to deep water. Reverse the engines and stop the vessel's forward movement. Turn in the direction of the deepest water before the vessel loses steerageway. Consider dropping the anchor to prevent the ship from drifting aground. The danger sounding indicates that the ship has left the channel and is standing into immediate danger. It requires immediate corrective action by the ship's conning officer, navigator, and captain to avoid disaster.

Many underwater features are poorly surveyed. If a fathometer trace of a distinct underwater feature can be obtained along with accurate position information, send the fathometer trace and related navigational data to NIMA for entry into the Digital Bathymetric Data Base.

PILOTING TO AN ANCHORAGE

816. Choosing an Anchorage

Most U.S. Navy vessels receive instructions in their movement orders regarding the choice of anchorage.

Merchant ships are often directed to specific anchorages by harbor authorities. However, lacking specific guidance, the mariner should choose his anchoring positions using the following criteria:

- **Depth of Water:** Choose an area that will provide sufficient depth of water through an entire range of tides. Water too shallow will cause the ship to go aground, and water too deep will allow the anchor to drag.
- **Type of Bottom:** Choose the bottom that will best hold the anchor. Avoid rocky bottoms and select sandy or muddy bottoms if they are available.
- **Proximity to navigational Hazards:** Choose an anchorage as far away as possible from known navigational hazards.
- **Proximity to Adjacent Ships:** Anchor well away from adjacent vessels; ensure that another vessel will not swing over your own anchor on a current or wind shift.
- **Proximity to Harbor Traffic Lanes:** Anchor clear of traffic lanes and ensure that the vessel will not swing into the channel on a current or wind shift.
- **Weather:** Choose an area with the weakest winds

and currents.

- **Availability of NAVAIDS:** Choose an anchorage with several NAVAIDS available for monitoring the ship's position when anchored.

817. Navigational Preparations for Anchoring

It is usually best to follow an established procedure to ensure an accurate positioning of the anchor, even when anchoring in an open roadstead. The following procedure is representative. See Figure 817.

Locate the selected anchoring position on the chart. Consider limitations of land, current, shoals, and other vessels when determining the direction of approach. Where conditions permit, make the approach heading into the current. Close observation of any other anchored vessels will provide clues as to which way the ship will lie to her anchor. If wind and current are strong and from different directions, ships will lie to their anchors according to the balance between these two forces and the draft and trim of each ship. Different ships may lie at different headings in the same anchorage depending on the balance of forces affecting them.

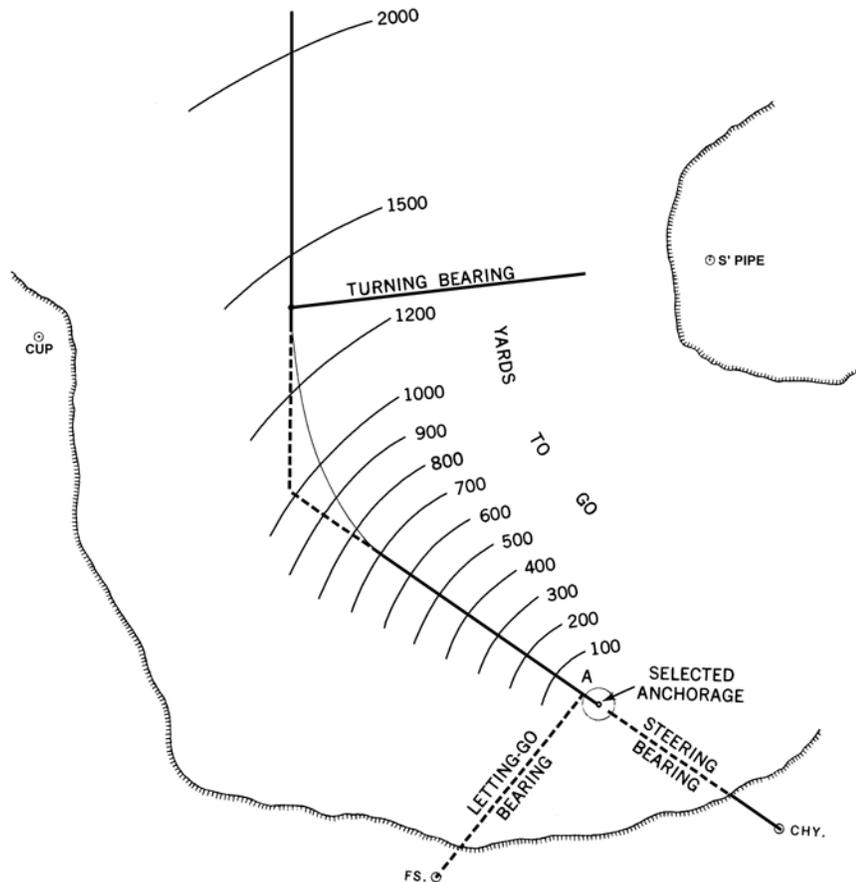


Figure 817. Anchoring.

Approach from a direction with a prominent NAVAID, preferably a range, available dead ahead to serve as a steering guide. If practicable, use a straight approach of at least 1200 yards to permit the vessel to steady on the required course. Draw in the approach track, allowing for advance and transfer during any turns. In Figure 817, the chimney was selected as this steering bearing. A turn range may also be used if a radar-prominent object can be found directly ahead or astern.

Next, draw a circle with the selected position of the anchor as the center, and with a radius equal to the distance between the hawsepipe and pelorus, alidade, or periscope used for measuring bearings. This circle is marked "A" in Figure 817. The intersection of this circle and the approach track is the position of the vessel's bearing-measuring instrument at the moment of letting the anchor go. Select a NAVAID which will be on the beam when the vessel is at the point of letting go the anchor. This NAVAID is marked "FS" in Figure 817. Determine what the bearing to that object will be when the ship is at the drop point and measure this bearing to the nearest 0.1° T. Label this bearing as the letting go bearing.

During the approach to the anchorage, plot fixes at frequent intervals. The navigator must advise the conning officer of any tendency of the vessel to drift from the desired track. The navigator must frequently report to the conning officer the distance to go, permitting adjustment of the speed so that the vessel will be dead in the water or have very slight sternway when the anchor is let go. To aid in determining the distance to the drop point, draw and label a number of range arcs as shown in Figure 817 representing distances to go to the drop point.

At the moment of letting the anchor go, take a fix and plot the vessel's exact position on the chart. This is important in the construction of the swing and drag circles discussed below. To draw these circles accurately, determine the position of the vessel at the time of letting go the anchor as accurately as possible.

Veer the anchor chain to a length equal to five to seven times the depth of water at the anchorage. The exact amount to veer is a function of both vessel type and severity of weather expected at the anchorage. When calculating the scope of anchor chain to veer, take into account the

maximum height of tide.

Once the ship is anchored, construct two separate circles around the ship's position when the anchor was dropped. These circles are called the **swing circle** and the **drag circle**. Use the swing circle to check for navigational hazards and use the drag circle to ensure the anchor is holding.

The swing circle's radius is equal to the sum of the ship's length and the scope of the anchor chain released. This represents the maximum arc through which a ship can swing while riding at anchor if the anchor holds. Examine this swing circle carefully for navigational hazards, interfering contacts, and other anchored shipping. Use the lowest height of tide expected during the anchoring period when checking inside the swing circle for shoal water.

The drag circle's radius equals the sum of the hawsepipe to pelorus distance and the scope of the chain released. Any bearing taken to check on the position of the ship should, if the anchor is holding, fall within the drag circle. If a fix falls outside of that circle, then the anchor is dragging. If the vessel has a GPS or Loran system with an off-station alarm, set the alarm at the drag circle radius, or slightly more.

In some cases, the difference between the radii of the swing and drag circles will be so small that, for a given chart scale, there will be no difference between the circles when plotted. If that is the case, plot only the swing circle and treat that circle as both a swing and a drag circle. On the other hand, if there is an appreciable difference in radii between the circles when plotted, plot both on the chart. Which method to use falls within the sound judgment of the navigator.

When determining if the anchor is holding or dragging, the most crucial period is immediately after anchoring. Fixes should be taken frequently, at least every three minutes, for the first thirty minutes after anchoring. The navigator should carefully evaluate each fix to determine if the anchor is holding. If the anchor is holding, the navigator can then increase the fix interval. What interval to set falls within the judgment of the navigator, but the interval should not exceed 30 minutes. If an ECDIS, Loran, or GPS is available, use its off-station alarm feature for an additional safety factor.

NAVIGATIONAL ASPECTS OF SHIP HANDLING

818. Effects Of Banks, Channels, and Shallow Water

A ship moving through shallow water experiences pronounced effects from the proximity of the nearby bottom. Similarly, a ship in a channel will be affected by the proximity of the sides of the channel. These effects can easily cause errors in piloting which lead to grounding. The effects are known as **squat**, **bank cushion**, and **bank suction**. They are more fully explained in texts on shiphandling, but certain navigational aspects are discussed

below.

Squat is caused by the interaction of the hull of the ship, the bottom, and the water between. As a ship moves through shallow water, some of the water it displaces rushes under the vessel to rise again at the stern. This causes a venturi effect, decreasing upward pressure on the hull. Squat makes the ship sink deeper in the water than normal and slows the vessel. The faster the ship moves through shallow water, the greater is this effect; groundings on both charted and uncharted shoals and rocks have occurred

because of this phenomenon, when at reduced speed the ship could have safely cleared the dangers. When navigating in shallow water, the navigator must reduce speed to avoid squat. If bow and stern waves nearly perpendicular the direction of travel are noticed, and the vessel slows with no change in shaft speed, squat is occurring. Immediately slow the ship to counter it. Squatting occurs in deep water also, but is more pronounced and dangerous in shoal water. The large waves generated by a squatting ship also endanger shore facilities and other craft.

Bank cushion is the effect on a ship approaching a steep underwater bank at an oblique angle. As water is forced into the narrowing gap between the ship's bow and the shore, it tends to rise or pile up on the landward side, causing the ship to sheer away from the bank.

ADVANCED PILOTING TECHNIQUES

819. Assuming Current Values to Set Safety Margins for Running Fixes

Current affects the accuracy of a running fix. Consider, for example, the situation of an unknown head current. In Figure 819a, a ship is proceeding along a coast, on course 250° speed 12 knots. At 0920 light A bears 190°, and at 0930 it bears 143°. If the earlier bearing line is advanced a distance of 2 miles (10 minutes at 12 knots) in the direction of the course, the running fix is as shown by the solid lines. However, if there is a head current of 2 knots, the ship is making good a speed of only 10 knots, and in 10 minutes will travel a distance of only $1\frac{2}{3}$ miles. If the first bearing line is advanced this distance, as shown by the broken line, the actual position of the ship is at B. This actual position is nearer the shore than the running fix actually plotted. A following current, conversely, would show a position too far from the shore from which the bearing was measured.

If the navigator assumes a following current when advancing his LOP, the resulting running fix will plot further from the NAVAID than the vessel's actual position. Conversely, if he assumes a head current, the running fix will plot closer to the NAVAID than the vessel's actual position. To ensure a margin of safety when plotting running fix bearings to a NAVAID on shore, always assume the current slows a vessel's speed over ground. This will cause the running fix to plot closer to the shore than the ship's actual position.

When taking the second running fix bearing from a different object, maximize the speed estimate if the second object is on the same side and farther forward, or on the opposite side and farther aft, than the first object was when observed.

All of these situations assume that danger is on the same side as the object observed first. If there is either a head or following current, a series of running fixes based

Bank suction occurs at the stern of a ship in a narrow channel. Water rushing past the ship on the landward side exerts less force than water on the opposite or open water side. This effect can actually be seen as a difference in draft readings from one side of the vessel to the other, and is similar to the venturi effect seen in squat. The stern of the ship is forced toward the bank. If the ship gets too close to the bank, it can be forced sideways into it. The same effect occurs between two vessels passing close to each other.

These effects increase as speed increases. Therefore, in shallow water and narrow channels, navigators should decrease speed to minimize these effects. Skilled pilots may use these effects to advantage in particular situations, but the average mariner's best choice is slow speed and careful attention to piloting.

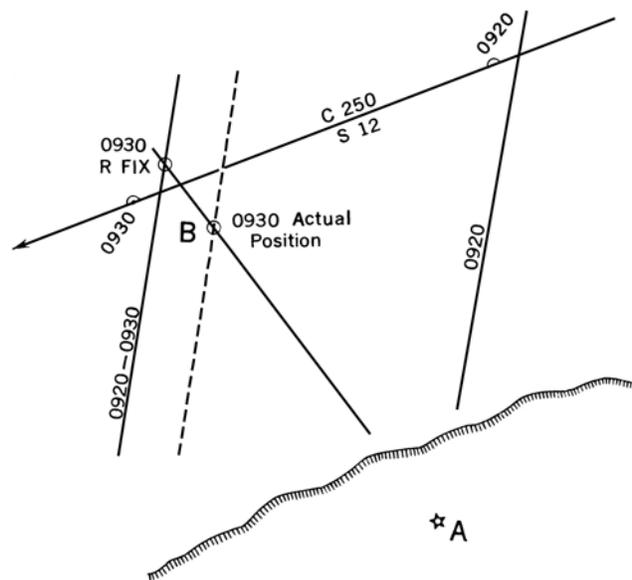


Figure 819a. Effect of a head current on a running fix.

upon a number of bearings of the same object will plot in a straight line parallel to the course line, as shown in Figure 819b. The plotted line will be too close to the object observed if there is a head current and too far out if there is a following current. The existence of the current will not be apparent unless the actual speed over the ground is known. The position of the plotted line relative to the dead reckoning course line is not a reliable guide.

820. Determining Track Made Good by Plotting Running Fixes

A current oblique to a vessel's course will also result in an incorrect running fix position. An oblique current can be detected by observing and plotting several bearings of the same object. The running fix obtained by advancing one

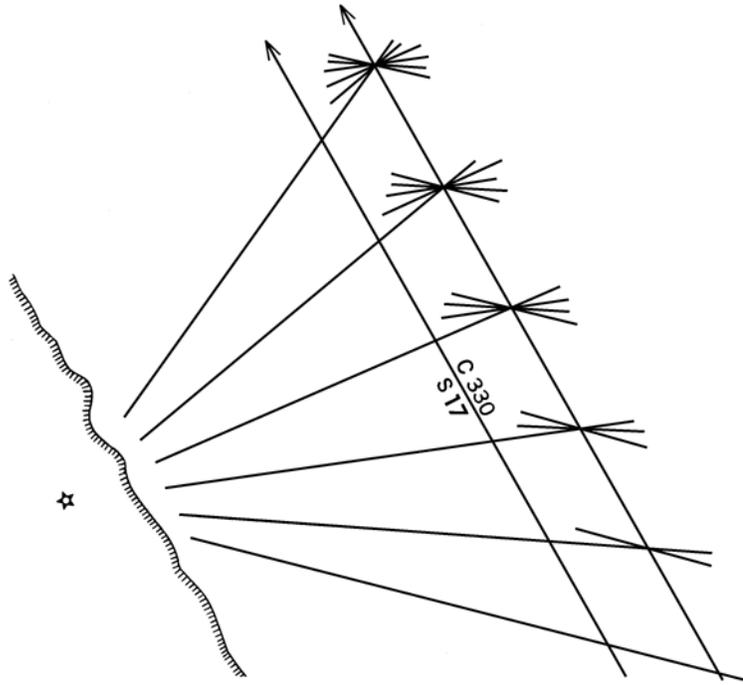


Figure 819b. A number of running fixes with a following current.

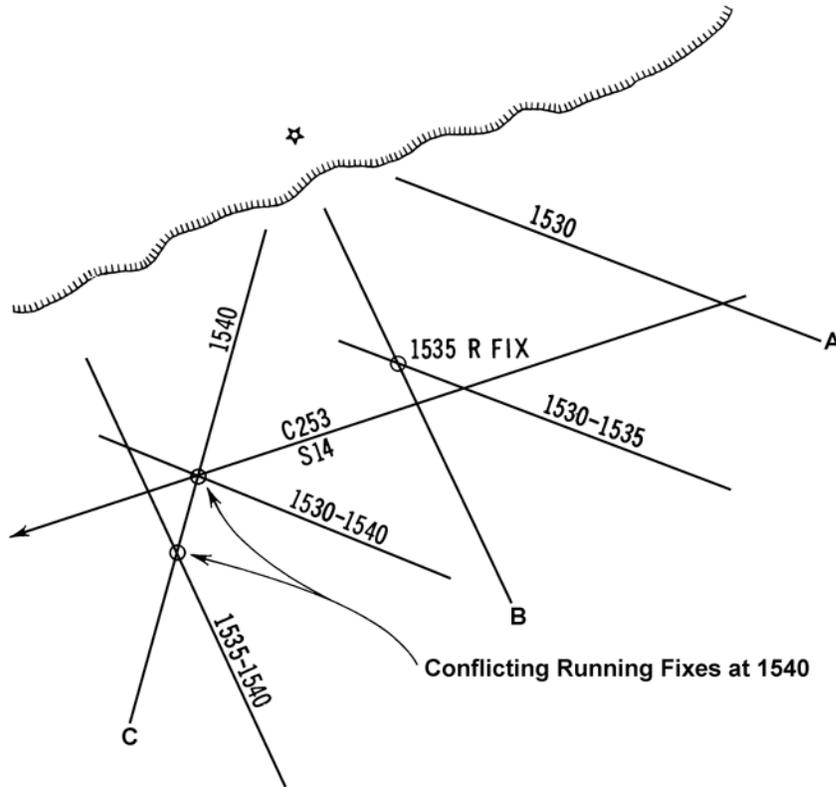


Figure 820a. Detecting the existence of an oblique current, by a series of running fixes.

bearing line to the time of the next one will not agree with the running fix obtained by advancing an earlier line. See Figure 820a. If bearings A, B, and C are observed at five-minute intervals, the running fix obtained by advancing B to the time of C will not be the same as that obtained by advancing A to the time of C, as shown in Figure 820a.

Whatever the current, the navigator can determine the direction of the track made good (assuming constant current and constant course and speed). Observe and plot three bearings of a charted object O. See Figure 820b. Through O draw XY in any direction. Using a convenient scale, determine points A and B so that OA and OB are proportional to the time intervals between the first and second bearings and the second and third bearings, respectively. From A and B draw lines parallel to the second bearing line, intersecting the first and third bearing lines at C and D, respectively. The direction of the line from C and D is the track made good.

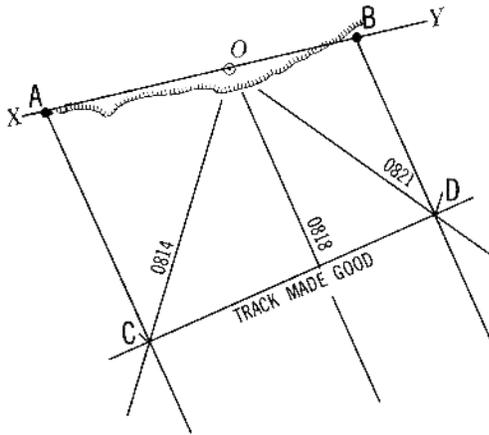


Figure 820b. Determining the track made good.

The distance of the line CD in Figure 820b from the track is in error by an amount proportional to the ratio of the speed made good to the speed assumed for the solution. If a good fix (not a running fix) is obtained at some time before the first bearing for the running fix, and the current has not changed, the track can be determined by drawing a line from the fix, in the direction of the track made good. The intersection of the track with any of the bearing lines is an actual position.

821. Fix by Distance of an Object by Two Bearings (Table 18)

Geometrical relationships can define a running fix. In Figure 821, the navigator takes a bearing on NAV AID D. The bearing is expressed as degrees right or left of course. Later, at B, he takes a second bearing to D; similarly, he takes a bearing at C, when the landmark is broad on the beam. The navigator knows the angles at A, B, and C and the distance run between points. The various triangles can be solved using Table 18.

From this table, the navigator can calculate the lengths of segments AD, BD, and CD. He knows the range and bearing; he can then plot an LOP. He can then advance these LOP's to the time of taking the CD bearing to plot a running fix.

Enter the table with the difference between the course and first bearing (angle BAD in Figure 821) along the top of the table and the difference between the course and second bearing (angle CBD) at the left of the table. For each pair of angles listed, two numbers are given. To find the distance from the landmark at the time of the second bearing (BD), multiply the distance run between bearings (in nautical miles) by the first number from Table 18. To find the distance when the object is abeam (CD), multiply the distance run between A and B by the second number from the table. If the run between bearings is exactly 1 mile, the tabulated values are the distances sought.

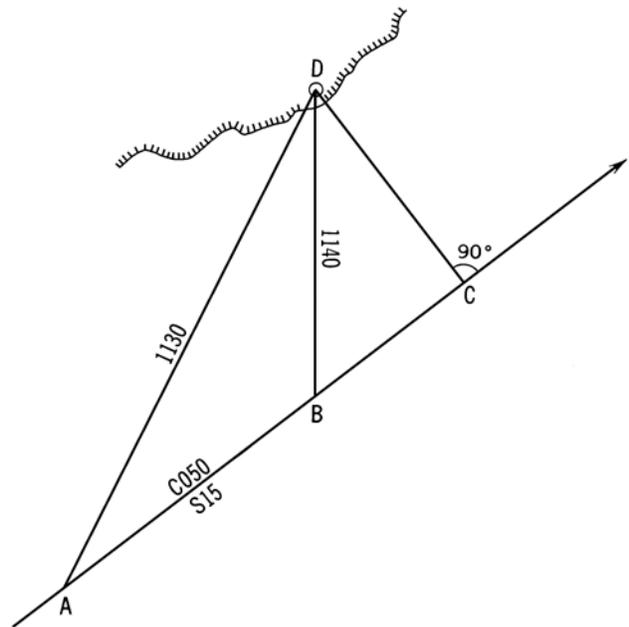


Figure 821. Triangles involved in a Table 18 running fix.

Example: A ship is steaming on course 050° , speed 15 knots. At 1130 a lighthouse bears 024° , and at 1140 it bears 359° .

Required:

- (1) Distance from the light at 1140.
- (2) Distance from the light when it is broad on the port beam.

Solution:

- (1) The difference between the course and the first bearing ($050^\circ - 24^\circ$) is 26° , and the difference between the course and the second bearing ($050^\circ + 360^\circ - 359^\circ$) is 51° .
- (2) From Table 18, the two numbers (factors are 1.04 and 0.81, found by interpolation).
- (3) The distance run between bearings is 2.5 miles (10 minutes at 15 knots).
- (4) The distance from the lighthouse at the time of the second bearing is $2.5 \times 1.04 = 2.6$ miles.

(5) *The distance from the lighthouse when it is broad on the beam is $2.5 \times 0.81 = 2.0$ miles.*

Answer: (1) D 2.6 mi., (2) D 2.0 mi.

This method yields accurate results only if the helmsman has steered a steady course and the navigator uses the vessel's speed over ground.

MINIMIZING ERRORS IN PILOTING

822. Common Errors

Piloting requires a thorough familiarity with principles involved, constant alertness, and judgment. A study of groundings reveals that the cause of most is a failure to use or interpret available information. Among the more common errors are:

1. Failure to obtain or evaluate soundings
2. Mis-identification of aids to navigation
3. Failure to use available navigational aids effectively
4. Failure to correct charts
5. Failure to adjust a magnetic compass or keep a table of corrections
6. Failure to apply deviation
7. Failure to apply variation
8. Failure to check gyro and magnetic compass readings regularly
9. Failure to keep a dead reckoning plot
10. Failure to plot new information
11. Failure to properly evaluate information
12. Poor judgment
13. Failure to use information in charts and navigational publications
14. Poor navigation team organization
15. Failure to "keep ahead of the vessel"
16. Failure to have backup navigational methods in place
17. Failure to recognize degradation of electronically obtained LOP's or lat./long. positions

Some of the errors listed above are mechanical and some are matters of judgment. Conscientiously applying the principles and procedures of this chapter will go a long way towards eliminating many of the mechanical errors. However, the navigator must guard against the feeling that in following a checklist he has eliminated all sources of error. A navigator's judgment is just as important as his checklists.

823. Minimizing Errors with a Two Bearing Plot

When measuring bearings from two NAVAIDS, the fix error resulting from an error held constant for both observations is minimized if the angle of intersection of the bearings is 90° . If the observer in Figure 823a is located at point T and the bearings of a beacon and cupola are observed and plotted without error, the intersection of the bearing lines lies on the circumference of a circle passing through the beacon, cupola, and the observer. With constant

error, the angular difference between the bearings of the beacon and the cupola is not affected. Thus, the angle formed at point F by the bearing lines plotted with constant error is equal to the angle formed at point T by the bearing lines plotted without error. From geometry it is known that angles having their apexes on the circumference of a circle and that are subtended by the same chord are equal. Since the angles at points T and F are equal and the angles are subtended by the same chord, the intersection at point F lies on the circumference of a circle passing through the beacon, cupola, and the observer.

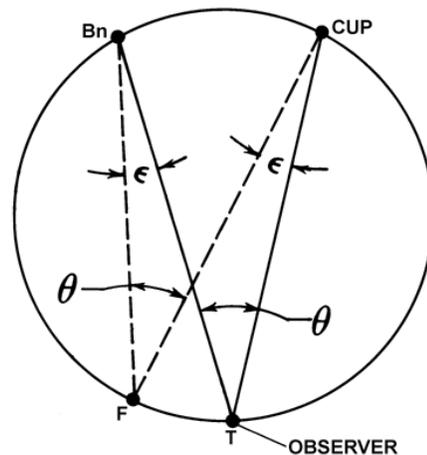


Figure 823a. Two-bearing plot.

Assuming only constant error in the plot, the direction of displacement of the two-bearing fix from the position of the observer is in accordance with the sign (or direction) of the constant error. However, a third bearing is required to determine the direction of the constant error.

Assuming only constant error in the plot, the two-bearing fix lies on the circumference of the circle passing through the two charted objects observed and the observer. The fix error, the length of the chord FT in Figure 823b, depends on the magnitude of the constant error ϵ , the distance between the charted objects, and the cosecant of the angle of cut, angle θ . In Figure 823b,

$$\text{The fix error} = FT = \frac{BC \csc \theta}{2}$$

where ϵ is the magnitude of the constant error, BC is the length of the chord BC, and θ is the angle of the LOP's intersection.

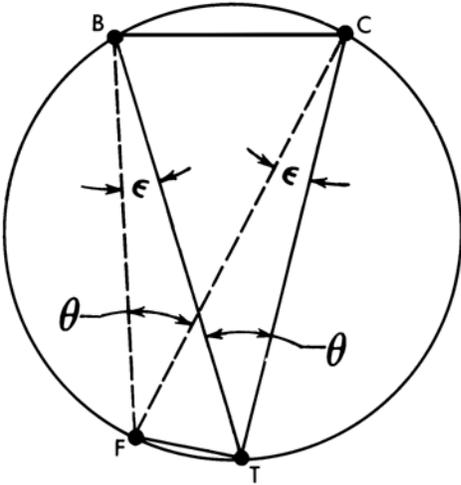


Figure 823b. Two-bearing plot with constant error.

Since the fix error is a function of the cosecant of the angle of intersection, it is least when the angle of intersection is 90° . As illustrated in Figure 823c, the error increases in accordance with the cosecant function as the angle of intersection decreases. The increase in the error becomes quite rapid after the angle of intersection has decreased to below about 30° . With an angle of intersection of 30° , the fix error is about twice that at 90° .

824. Finding Compass Error by Trial and Error

If several fixes obtained by bearings on three objects produce triangles of error of about the same size, there might be a constant error in observing or plotting the bearings. If applying of a constant error to all bearings results in a pinpoint fix, apply such a correction to all subsequent fixes. Figure 824 illustrates this technique. The solid lines indicate the original plot, and the broken

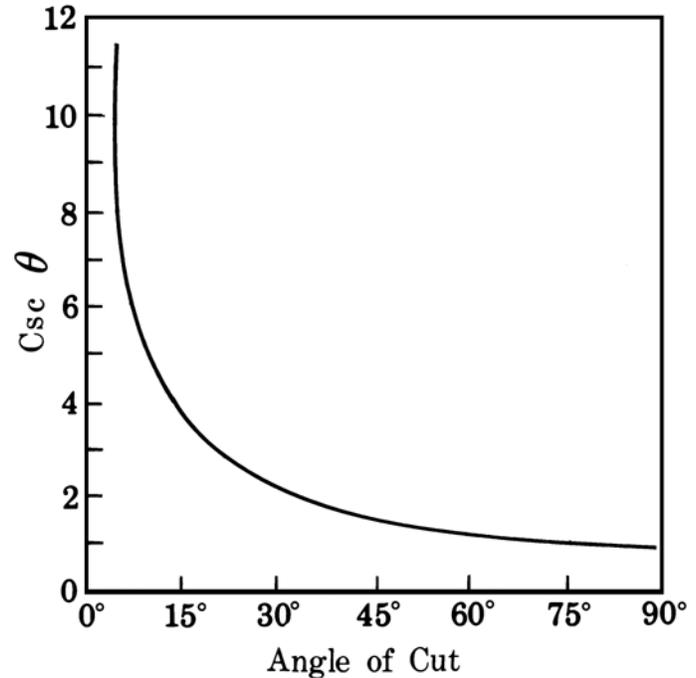


Figure 823c. Error of two-bearing plot.

lines indicate each line of position moved 3° in a clockwise direction.

Employ this procedure carefully. Attempt to find and eliminate the error source. The error may be in the gyrocompass, the repeater, or the bearing transmission system. Compare the resulting fix positions with a satellite position, a radar position, or the charted sounding. A high degree of correlation between these three independent positioning systems and an "adjusted" visual fix is further confirmation of a constant bearing error.

TRAINING

825. Piloting Simulators

Civilian piloting training has traditionally been a function of both maritime academies and on-the-job experience. The latter is usually more valuable, because there is no substitute for experience in developing judgment. Military piloting training consists of advanced correspondence courses and formal classroom instruction combined with duties on the bridge. U.S. Navy Quartermasters frequently attend Ship's Piloting and Navigation (SPAN) trainers as a routine segment of shoreside training. Military vessels in general have a much clearer definition of responsibilities, as well as more people to carry them out, than civilian ships, so training is generally more thorough and targeted to specific skills.

Computer technology has made possible the

development of computerized **ship simulators**, which allow piloting experience to be gained without risking accidents at sea and without incurring underway expenses. Simulators range from simple micro-computer-based software to a completely equipped ship's bridge with radar, engine controls, 360° horizon views, programmable sea motions, and the capability to simulate almost any navigational situation.

A different type of simulator consists of scale models of ships. The models, actually small craft of about 20-30 feet, have hull forms and power-to-weight ratios similar to various types of ships, primarily supertankers, and the operator pilots the vessel from a position such that his view is from the craft's "bridge." These are primarily used in training pilots and masters in docking maneuvers with exceptionally large vessels.

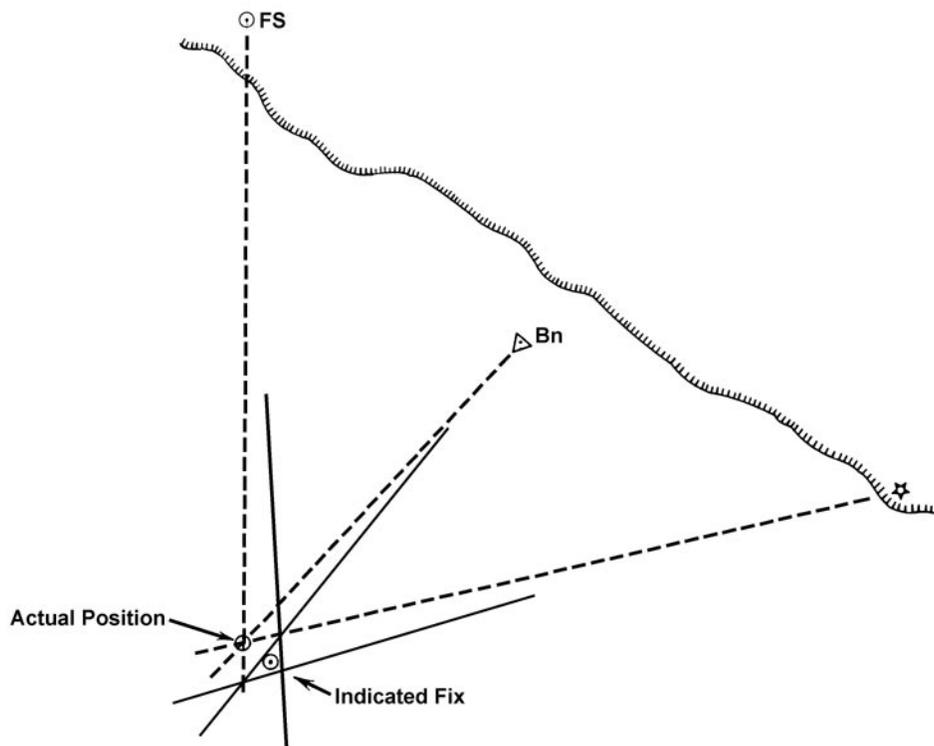


Figure 824. Adjusting a fix for constant error.

The first computer ship simulators came into use in the late 1970s. Several years later the U.S. Coast Guard began accepting a limited amount of simulator time as “sea time” for licensing purposes. They can simulate virtually any conditions encountered at sea or in piloting waters, including land, aids to navigation, ice, wind, fog, snow, rain, and lightning. The system can also be programmed to simulate hydrodynamic effects such as shallow water, passing vessels, current, and tugs.

Virtually any type of vessel can be simulated, including tankers, bulkers, container ships, tugs and barges, yachts, and military vessels. Similarly, any given navigational situation can be modeled, including passage through any chosen harbor, river, or passage, convoy operations, meeting and passing situations at sea and in harbors.

Simulators are used not only to train mariners, but also to test feasibility of port and harbor plans and visual aids to navigation system designs. This allows pilots to “navigate” simulated ships through simulated harbors before construction begins to test the adequacy of channels, turning basins, aids to navigation, and other factors.

A full-capability simulator consists of a ship’s bridge which may have motion and noise/vibration inputs, a programmable visual display system which projects a simulated picture of the area surrounding the vessel in both daylight and night modes, image generators for the various inputs to the scenario such as video images and radar, a central data processor, a human factors monitoring system which may record and videotape bridge activities for later analysis, and a control station where instructors control the entire scenario.

Some simulators are part-task in nature, providing specific training in only one aspect of navigation such as radar navigation, collision avoidance, or night navigation.

While there is no substitute for on-the-job training, simulators are extremely cost effective systems which can be run for a fraction of the cost of an actual vessel. Further, they permit trainees to learn from mistakes with no possibility of an accident, they can model an infinite variety of scenarios, and they permit replay and reassessment of each maneuver.